Sketching and alternating projections for low-rank nonnegative matrix and tensor decompositions

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## Outline

- 1. Problem setup, short history
- 2. Test cases for nonnegative matrices/functions
- 3. Randomized SVD and complexity reduction
- 4. First observations for tensors in Tucker and TT-formats

## Problem setup

Let

- $A \in \mathbb{R}^{m \times n}$ ,  $A_{i,j} \geq 0$ ,
- $A \approx A_r$ , rank $A^r = r$ ,
- $||A A^r||_F \ll 1.$

Can we guarantee

 $A_{i,j}^{r} \ge 0?$ 

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## Problem setup, NMF approach

Let

- $A \in \mathbb{R}^{m \times n}$ ,  $A_{i,j} \ge 0$ , •  $A \approx A^{(r)}$ , rank $A^{(r)} = r$ ,
- $||A A^{(r)}||_F \ll 1.$

#### Way I

Construct a nonnegative matrix factorization

$$A = U \cdot V^{T}, U \in \mathbb{R}^{m \times r}, V \in \mathbb{R}^{n \times r},$$

Subject to

$$U_{i,j}, V_{i,j} \geq 0.$$

Problems:

- 1. nonnegative rank is often greater than usual(rank\_+)  $\geq$  rank
- 2. NP-hard task
- 3. Iterative methods require a lot of computing and requre significant efforts in theory
- 4. Nonnegative factors are not always necessary

## Problem setup, NMF approach

Way I: NMF NMF construction task

$$egin{aligned} A &= U \cdot V^{\mathcal{T}}, U \in \mathbb{R}^{m imes r}, V \in \mathbb{R}^{n imes r}, \ U_{i,j}, V_{i,j} \geq 0. \end{aligned}$$

- 1. nonnegative rank is often greater than usual(rank<sub>+</sub>)  $\geq$  rank
- 2. NP-hard task
- 3. Iterative methods require a lot of computing and requre significant efforts in theory
- 4. Nonnegative factors are not always necessary

#### References:

- 1. Gillis N. Nonnegative matrix factorization. Society for Industrial and Applied Mathematics, 2020.
- Tyrtyshnikov E. E., Shcherbakova E. M. Methods for nonnegative matrix factorization based on low-rank cross approximations //Computational Mathematics and Mathematical Physics. 2019. T. 59. №. 8.

## Problem setup, LRNMF

#### Way II: LRNMF

Construct low-rank nonnegative matrix factorization

$$egin{aligned} A &= U \cdot V^T, U \in \mathbb{R}^{m imes r}, V \in \mathbb{R}^{n imes r}, \ U_{i,j}, V_{i,j} &: A_{i,j}^{(r)} \geq 0 \end{aligned}$$

- 1. Nonnegative factors are **not** necessary U, V
- 2. Thus, we seek to get element from intersection of two sets: (I) low-rank matrices ( $\leq r$ ) and (II) nonnegative matrices

- 3. Set I  $(M_{\geq 0})$  is convex
- 4. Set II  $(M_{\text{rank}A \leq r})$ : low-rank matrices  $(\leq r)$  is smooth
- 5. For both  $M_{\geq 0}$  and  $M_{\operatorname{rank}A \leq r}$  there are projection operators.

Hence, let us use alternating projections.

#### Alternating projections, 2020

$$\Pi_{\mathcal{M}_{\leq r}}(X) = \mathrm{SVD}_r(X) = U_r \Sigma_r V_r^{\ I} = \arg\min_{Y \in \mathcal{M}_{\leq r}} \|X - Y\|_F,$$

$$\Pi_{\mathbb{R}^{m \times n}_+}(X) = \max(X, 0) = \{\max(x_{ij}, 0)\} = \arg \min_{Y \in \mathbb{R}^{m \times n}_+} \|X - Y\|_{F}.$$

Song G. J., Ng M. K. Nonnegative low rank matrix approximation for nonnegative matrices //Applied Mathematics Letters. – 2020. – Vol. 105.

Complexity  $O(mn^2 + mn)$ 

Algorithm 1: Exact alternating projections (SVD)

 $\begin{array}{l} \textbf{Data: Initial approximation } Y^{(0)} \in \mathbb{R}^{m \times n} \text{ of rank } r, \text{ number of } \\ \text{iterations } s \\ \textbf{for } i = 1, \ldots, s \text{ do} \\ & \left| \begin{array}{c} X^{(i)} \leftarrow \max(Y^{(i-1)}, 0); \\ [U_r, \Sigma_r, V_r] \leftarrow \operatorname{SVD}_r(X^{(i)}); \\ Y^{(i)} \leftarrow U_r \Sigma_r V_r^T; \\ \textbf{end} \\ \textbf{return } Y^{(s)} \end{array} \right.$ 

## Test function

Possible functions/data:

- Images (BW, RGB, multispectral)
- Solutions of PDEs and related models in higher dimensions (Chemical master equation, Fokker-Planck equation, population balance equations etc)
- Probability distributions

In all cases low-rank matrices and tensors are useful.

## Test function

Solution of the two-component Smoluchowski equtaion

$$\begin{aligned} \frac{\partial n(v_1, v_2, t)}{\partial t} &= -n(v_1, v_2, t) \int_0^\infty \int_0^\infty K(u_1, u_2; v_1, v_2) n(u_1, u_2, t) du_1 du_2 \\ &+ \frac{1}{2} \int_0^{v_1} \int_0^{v_2} K(v_1 - u_1, v_2 - u_2; u_1, u_2) n(v_1 - u_1, v_2 - u_2, t) n(u_1, u_2, t) du_1 du_2, \end{aligned}$$

For case of constant kernel function

$$K(u_1, u_2; v_1, v_2) \equiv K,$$

and initial condition

$$n(v_1, v_2, t=0) = \sqrt{K}abe^{-av_1-bv_2},$$

there is a known analytical solution(it has good *low-rank* approximations!)

$$n(v_1, v_2, t) = \sqrt{K} \frac{abe^{-av_1 - bv_2}}{(1 + \sqrt{K}t/2)^2} I_0\left(2\sqrt{\frac{abv_1v_2\sqrt{K}t}{\sqrt{K}t + 2}}\right),$$

#### Test function

Matveev S. A. et al. Tensor train versus Monte Carlo for the multicomponent Smoluchowski coagulation equation //Journal of Computational Physics. – 2016. – T. 316.



#### How does it work?



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#### Can we go faster? Yes, via tangent projections

$$T_{Y}\mathcal{M}_{r} = \left\{ U_{r}A^{T} + BV_{r}^{T} : A \in \mathbb{R}^{n \times r}, \quad B \in \mathbb{R}^{m \times r} \right\},$$
$$\Pi_{T_{Y}\mathcal{M}_{r}}(X) = U_{r}U_{r}^{T}X + (I - U_{r}U_{r}^{T})XV_{r}V_{r}^{T}.$$
$$\tilde{\Pi}_{\mathcal{M}_{\leq r}}(X) = \mathrm{SVD}_{r}(\Pi_{T_{Y}\mathcal{M}_{r}}(X)).$$

Song G., Ng M. K., Jiang T. X. Tangent Space Based Alternating Projections for Nonnegative Low Rank Matrix Approximation //arXiv preprint arXiv:2009.03998. – 2020.

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Can we go faster? Yes, via tangent projections Song G., Ng M. K., Jiang T. X. Tangent Space Based Alternating Projections for Nonnegative Low Rank Matrix Approximation //arXiv preprint arXiv:2009.03998. – 2020.

Complexity O(mnr)

Algorithm 2: Alternating projections via tangent spaces (Tangent)

 $\begin{aligned} & \textbf{Data: Initial approximation } Y^{(0)} \in \mathbb{R}^{m \times n} \text{ of rank } r, \text{ number of iterations } s \\ & [U_r, \Sigma_r, V_i] \leftarrow \text{SVD}_r(Y^{(0)}); \\ & \textbf{for } i = 1, \dots, s \textbf{ do} \\ & X^{(i)} \leftarrow \max(Y^{(i-1)}, 0); \\ & G_1 \leftarrow U_r^T X^{(i)} \in \mathbb{R}^{r \times n}, \quad G_2 \leftarrow (I - U_r U_r^T) X^{(i)} V_r \in \mathbb{R}^{m \times r}; \\ & [Q_1, R_1] \leftarrow \text{QR}(G_1^T), \quad [Q_2, R_2] \leftarrow \text{QR}(G_2); \\ & Z \leftarrow \begin{bmatrix} G_1 V_r & R_1^T \\ R_2 & 0 \end{bmatrix} \in \mathbb{R}^{2r \times 2r}; \\ & [\tilde{U}_r, \Sigma_r, \tilde{V}_r] \leftarrow \text{SVD}_r(Z); \\ & U_r \leftarrow \begin{bmatrix} U_r & Q_2 \end{bmatrix} \tilde{U}_r, \quad V_r \leftarrow \begin{bmatrix} V_r & Q_1 \end{bmatrix} \tilde{V}_r; \\ & Y^{(i)} \leftarrow U_r \Sigma_r V_r^T; \end{aligned}$ 

end

return  $Y^{(s)}$ 

## Can we use sketching?

# Answer: Yes! Just replace the original SVD by randomized SVD (and check various sketchings)

Matveev S. A., Budzinskiy S. Sketching for low-rank nonnegative matrix approximation: a numerical study //arXiv preprint arXiv:2201.11154. – 2022.

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Algorithm 3: Alternating projections via HMT
Data: Initial approximation Y^{(0)} \in \mathbb{R}^{m \times n} of rank r, co-range sketch
            size k > r, number of power method iterations p, test matrix
            generator TESTMATRIX, number of iterations s
for i = 1, ..., s do
      X^{(i)} \leftarrow \max(Y^{(i-1)}, 0):
      \Psi \leftarrow \text{TestMatrix}(n,k) \in \mathbb{R}^{n \times k};
      Z_1 \leftarrow X^{(i)} \Psi \in \mathbb{R}^{m \times k}
      [Q, R] \leftarrow QR(Z_1);
      for j = 1, ..., p do
           Z_2 \leftarrow Q^T X^{(i)} \in \mathbb{R}^{k \times n}
       [Q, R] \leftarrow \operatorname{QR}(Z_2^T);

Z_1 \leftarrow X^{(i)}Q \in \mathbb{R}^{m \times k};

[Q, R] \leftarrow \operatorname{QR}(Z_1);
       end
      Z_2 \leftarrow Q^T X^{(i)} \in \mathbb{R}^{k \times n};
      \begin{bmatrix} U_r, \Sigma_r, V_r \end{bmatrix} \leftarrow \text{SVD}_r(Z_2);

Y^{(i)} \leftarrow QU_r \Sigma_r V_r^T;
end
return Y<sup>(s)</sup>
```

#### Convergence tests



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## FLOPs comparison

Method	Sketch	Flops (init/per iter)	$  arepsilon  _F$ (init/res)
SVD	N/A	$2.3\cdot 10^{10}/2.3\cdot 10^{10}$	$2.39\cdot 10^{-2}/2.70\cdot 10^{-2}$
Tangent	N/A	$2.3 \cdot 10^{10} / 6.5 \cdot 10^7$	$2.39 \cdot 10^{-2} / 2.72 \cdot 10^{-2}$
HMT(0, 15)	Rad(0.2)	$3.7 \cdot 10^7 / 5.8 \cdot 10^7$	$2.43 \cdot 10^{-2} / 2.75 \cdot 10^{-2}$
Tropp(15, 25)	Rad(0.2)	$1.2 \cdot 10^7 / 3.3 \cdot 10^7$	$2.43 \cdot 10^{-2} / 2.87 \cdot 10^{-2}$
GN(40)	Rad(0.2)	$1.2 \cdot 10^7/3.3 \cdot 10^7$	$8.47\cdot 10^{-2}/1.83\cdot 10^{-1}$

Test case: 1000 iterations with rank-10 LRNMF approximations for "Smoluchowski" matrix 1024  $\times$  1024.

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## Tensors, Tucker format

*Tucker format* is a following decomposition for tensor  $A \in \mathbb{R}^{n_1 \times \cdots \times n_d}$ :

$$A = G \times_1 U_1 \cdots \times_d U_d,$$

where  $G \in \mathbb{R}^{r_1 \times \cdots \times r_d}$ ,  $U_1 \in \mathbb{R}^{r_1 \times n_1}, \dots, U_d \in \mathbb{R}^{r_d \times n_d}$ .



How to modify alternating projections?

- HOSVD may replace basic SVD
- Randomized SVD can be easily incorporated and reduce complexity from  $O(N^{d+1})$  to  $O(N^d)$

## Tensors, TT-format

*Tensor Train* is a following decomposition for tensor  $A \in \mathbb{R}^{n_1 \times \cdots \times n_d}$ :  $A \in \mathbb{R}^{n_1 \times \cdots \times n_d}$  as following

$$A(i_1,\ldots,i_d)=\sum_{\alpha_0,\ldots,\alpha_d}G_1(\alpha_0,i_1,\alpha_1)G_2(\alpha_1,i_2,\alpha_2)\ldots G_d(\alpha_{d-1},i_d,\alpha_d),$$

where  $G_k \in \mathbb{R}^{r_{k-1} \times n_k \times r_k}$ 



How to modify alternating projections? The very same trick

- TTSVD may also replace basic SVD :)
- Randomized SVD can be easily incorporated and reduce complexity from O(N<sup>d+1</sup>) to O(N<sup>d</sup>)

## HO-SVD and TT-SVD



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## HO-SVD and TT-SVD



TTSVD graphical representation

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Oseledets I. V., Tyrtyshnikov E. E. (2009). Breaking the curse of dimensionality, or how to use SVD in many dimensions. SIAM Journal on Scientific Computing, 31(5), 3744-3759.

## Test case: mixture of three multidimensional Gaussians

Test case: tensor modes  $118 \times 128 \times 138$ .

Three random covariance matrices for Gaussians.

Tensor is generated as elementwise sum of these three tensors.



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We see the very same results for this test but in TT-format.

- 1. Sketching and randimozed SVD work fine for alternating projections for low-rank nonnegative matrix factorizations.
- 2. Our observations can be also generalized for tensors in TT and Tucker formats
- 3. Main task (challenge?) for future: find a way of reduction of complexity for projector onto  $M_{\geq 0}$  and  $T_{\geq 0}$  sets

## Thank you for attention!<sup>1</sup>.

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Preprint for matrix case is available Matveev S. A., Budzinskiy S. Sketching for low-rank nonnegative matrix approximation: a numerical study //arXiv preprint arXiv:2201.11154. – 2022.

Paper with tests for tensors is almost ready.